DEPARTMENT OF MECHANICAL ENGINEERING AND MECHANICS COLLEGE OF ENGINEERING AND TECHNOLOGY OLD DOMINION UNIVERSITY NORFOLK, VIRGINIA 23508

COMPONENT MODE SYNTHESIS AND LARGE DEFLECTION VIBRATION OF COMPLEX STRUCTURES

VOLUME 1:

EXAMPLES OF NASTRAN® MODAL SYNTHESIS

CAPABILITY

LANGLE/ GRANT 1N-39-CR 93405

Ву

Chuh Mei, Principal Investigator

and

Mo-How Shen

Final Report For the period ended January 31, 1987

Prepared for the National Aeronautics and Space Administration Langley Research Center Hampton, VA 23665

Under Research Grant NAG-1-301 Mr. Joseph E. Walz, Technical Monitor SDD-Structural Dynamics Branch

(NASA-CR-181290) COMPONENT BODE SYNTHESIS AND LARGE DEFLECTION VIERATION OF COMPLEX STRUCTURES. VOLUME 1: EXAMPLES OF NASTRAN MCDAL SYNTHESIS CAPABILITY Final Report, period ending 31 Jan. (Cld Complete Univ.)

N87-28045

G3/39 Unclas G3/39 0093405

August 1987

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Submitted by the Old Domnion University Research Foundation P.O. Box 6369
Norfolk, Virginia 23508

SUMMARY

This report illustrates the use of NASTRAN® modal synthesis capability for some small examples. A classical truss problem is examined and the results for accuracy are compared to existing results from other methods. This problem is examined using both fixed interface modes and tree interface modes. The solution is carried out for an applied dynamic load down as far as recovery of forces in individual members as a function of time. Another small beam problem is used to compare different means of "combining" substructures.

INTRODUCTION

During the past twenty years, a body of technology has developed within the general field of structural dynamics that has been identified by the term modal synthesis. Modal synthesis is a Rayleigh-Ritz approach using systematically derived displacement functions. It is used to formulate and solve the large eigen problems which arise in dynamic analysis of complex structural systems. Solutions are approximate in the sense that the motion of the structure is constrained to linear combinations of a limited number of modes or displacement functions characterizing the behavior of independent substructures.

Several researchers have formulated various modal synthesis procedures in an attempt to reduce computation errors and minimize computer costs. Hurty developed the first modal synthesis method capable of analyzing structures with redundant interface connections in references 1 and 2. He treated the structure as an assembly of connected components, or substructures, each of which is analyzed separately to derive a set of modes or displacement shapes from which a set of generalized coordinates applicable to the complete structure is synthesized. Craig and Bampton (ref. 3) simplified Hurty's formulation by combining two groups of coordinate functions which Hurty had defined separately. A number of survey papers have been written by Hou, Goldman, Benfield and Hruda in references 4 to 7. Some methods are found to be more suitable for certain applications than others. Yet, experience has shown that no single approach is generally preferred over the others.

The complexity of aerospace structures increased enormously during the last two decades. A new challenge is presented by the proposed space station (ref. 8) in that it is an evolving structure that cannot be ground tested because final configuration may not be known when the first component is put into space. Therefore, the component mode synthesis method may be applied for the dynamic analysis of such large structure system in space. A widely used tool for structural analysis, the NASTRAN® computer program, contains a modal synthesis capability but, other than the demonstration problem presented in reference 5, little is publicly known about its capabilities.

The purpose of the present report is to examine some of the capabilities of this program. This is done by examining two simple problems, a truss and a beam.

NUMERICAL EXAMPLES

The modal synthesis procedure in NASTRAN® is applied to two simple structures. One is a redundant truss confined to lie in a plane but free to move in this plane. It is composed entirely of ROD elements (no bending stiffness for all). This example is used to examine convergence character—

istics of the modal synthesis procedure and also to illustrate the transient response capability all the way down to obtaining stresses in rod members as a function of time. The second example is a free-free beam. It is used to examine different ways to "combine" substructures to yield frequency for the total structure.

Truss Example

The redundant truss example is the one used in reference 5 to compare eight different modal synthesis procedures. The full truss model is shown in figure 1(a) and its two components shown in figure 1(b). Component A consists of five equal bays and has a total of 18 joints. Component B consists of four equal bays and has a total of 15 joints. All members in the components have identical properties. At the interface of the components in the full truss model, the vertical member has twice the area of other members. Basic geometric and material properties are presented in table I along with the prescribed load for a transient response analysis. An additional run was made with the full model subdivided into three components with three bays in each component.

The basic run sequence and substructure operation are shown in figure 2. In the figure capitalized letters inside of rectangular blocks indicate names of psuedostructures used in the analysis. Capitalized letters adjacent to, or on, the flow diagram indicate the names of modules that perform a certain function in the computer program. At the top of figure 2, the Phase 1 operations formulate the finite element stiffness and mass matrices using Rigid Format 2. For the convergence study the Phase 2 runs on Rigid Format 3 were repeated using a different number of modes from the individual components. Also Phase 2 runs were using free interface modes as well as the fixed interface modes. A limited amount of data is presented for three components and naturally a Phase 1 run must be made for this component.

A transient response analysis was made on this free-free truss structure for an axial load applied to the right end of the truss. The load was applied for 0.12 seconds and then removed. In order to apply a load at grid point 42 in component B, this grid point must be included on a BOUNDARY

card. Thus, additional degrees of freedom are created corresponding to this point. The structure was represented by eight modes from component A, six modes from component B, and the eight interface modes for a total of twenty-two modes. The modes for the individual component were determined with the interface fixed. The standard procedure will obtain displacements back in the individual component. However, member forces and stresses are not determined automatically, but can be obtained through a simple procedure in a few steps. In the first step a run is made with DIAG 17 turned on to put the DMAP sequence on the punch file with an EXIT scheduled after statement 1. A small substructure deck is included to allow the appropriate commands that interface to the Substructures Operating File (SOF) to be generated. This punch file is subsequently saved and altered to replace the RECOVER module with the SDR2 module which can recover element forces and stresses. The listing of this DMAP sequence and run stream is contained in Appendix A.

Beam Example

This example consists of a beam composed of seven components as shown in figure 3(a). All subbeams have a constant length, area and uniform mass properties. Each component consists of ten equal elements and has a total of 11 joints as shown in figure 3(b). Basic geometric and material properties for each subbeam are presented in table II. A lumped mass formulation is used (no rotary inertia) and, therefore, there are 213 stiffness degrees of freedom in the problem, but only 142 eigenvalues.

Three different ways of "combining" substructures are illustrated in figures 3(c), 3(d), and 3(e). The basic run sequences and substructure operations for each case are shown in figures 4 thru 6. For all cases, the substructuring Phase 1 operations formulate the finite element stiffness and mass matrices for subbeam A using Rigid Format 3. The structural matrices contained in BBASIC, CBASIC, ..., FBASIC are generated as needed by using EQUIV operation. The basic subbeams are reduced to modal coordinates and combined together following the procedures shown in figures 4 thru 6. The eigenvalues of the total beam are obtained by using the MRECOVER command. The driver decks and sample bulk data for cases 1, 2 and 3 are listed in Appendices B, C and D. Only fixed interface modes were used but two sets of runs were made using a different number of modes from the subbeams.

RESULTS

For assessing the accuracy of the modal synthesis procedure, two and three truss components with fixed or free interface connection are run to determine frequencies and compared to results for full model. Percentage errors in frequency for the combined systems of 12, 20, 28 and 36 degrees of freedom are shown in tables III thru VI. Here degrees of freedom include not only the number of flexible modes used but also any interface modes. Thus, for example, for 12 degrees of freedom results, since there are six interface modes, only six flexible modes can be shown. Based on the lowest frequency criterion then four modes were chosen from component A and two modes from component B.

Figures 7 thru 11 are nondimensional plots that indicate the relative accuracy obtained by modal synthesis procedures. Also shown on the figures are results taken directly from reference 5 in which several other procedures are compared. From figures 7 to 10 it can be seen that modes derived with the interfaces fixed yield better results than modes derived with the interface free.

For the transient response run the percentage error in displacement for grid points 41, 42, and 43 of component B are shown in table VII. These results were produced from the 20 degrees of freedom model. The axial force in elements 111-113 and 143 of component B are shown in table VIII.

The full beam shown in figure 2 was run to determine its natural frequencies and used as a comparison of results obtained with the various "combination" procedures. Table IX shows the percentage error in frequency for the various "combination" procedures when 62 degrees of freedom are used. These 62 degrees of freedom correspond to approximately 47% of the total degrees of freedom in the full model. All three "combination" procedures yield good results. However, case 1 uses considerably less CYBER 75 CPU time than the other two cases (53.8 CPU seconds corresponds to 65.3 seconds, 59.1 seconds, respectively). Another run for case 1 was made using 19% of total degrees of freedom, and 55% frequencies were obtained with less than 1% error in frequency.

ACKNOWLEDGEMENT

This work was sponsored by the NASA-Langley Research Center under Grant NAG-1-301. The work was monitored under the supervision of Dr. Jerrold M. Housner and Mr. Joseph E. Walz, Structural Dynamics Branch, Structures and Dynamics Division. Mr. Mo-How Shen, a graduate student in the Department of Mechanical Engineering and Mechanics, Old Dominion University, carried out most of the detailed studies. The author would like to thank Mr. Joe Walz for many valuable suggestions and assistance.

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Table I. Truss Geometric and Material Properties

	
Typical frame width (see fig. l(b))	a = 1.015 m (40")
Typical frame height (see fig. 1(b))	h = 0.762 m (30")
Cross-sectional area of members	$A = 1.935 \text{ cm}^2 (0.3 \text{ in}^2)$
Young's modulus	$E = 1.422 \times 10^4 \frac{\text{Kg}}{\text{m}^2} (10^7 \text{ psi})$
Density	$\rho = 272.517 \text{ Kg-sec}^{2}$ m^{4} $(2.5 \times 10^{-4} \frac{1 \text{bf-sec}^{2}}{\text{in}^{4}})$
Transient loads	$P_{42} = 2.2 \times 10^{3} \text{Kg} (10^{3} 1\text{bf}) 0 < t < 0.12S$ $0 \qquad t > 0.12S$

Table II. Beam Geometric and Material Properties

Typical component length (see fig. 3(b))	l = 2.54 m (100")
Cross section of beam	$A = 3.613 \text{ cm}^2 (0.56 \text{ in}^2)$
Young's modulus	$E = 1.422 \times 10^4 \frac{\text{Kg}}{\text{m}^2} (10^7 \text{psi})$
Density	$\rho = 282.437 \frac{\text{Kg-sec}^2}{\text{m}^4}$ $(2.591 \times 10^{-4} \frac{1 \text{bf-sec}^2}{\text{in}^4})$
Total beam length	L = 15.78 m (700")

Table III. Frequency for Full Truss and Percent Error in Frequency for Two Modal Synthesis Models Using 12 Degrees of Freedom

Mode No.	Full Truss (Hz)	Free Interface (%)	Fixed Interface (%)
1	65.7771	29.88	0.0015
2	136.3306	4.32	0.0022
3	175.5505	21.9	0.0314
4	202.7780	7.35	0.0198
5	260.3387	3.49	0.0536
6	316.2614	5.12	0.0227
7	334.1522	61.41	4.21
8	347.1668	142.05	6.439
9	388.1286	183.78	0.97

Table IV. Frequency for Full Truss and Percent Error in Frequency for Two Modal Synthesis Models Using 20 Degrees of Freedom

Mode No.	Full Truss (Hz)	Free Interface (%)	Fixed Interface (%)	3 Components Fixed Interface
i	65.7771	19.23	0.00074	0.00351
2	136.3306	2.82	0.00044	-0.03425
3	175.5505	8.2	0.0087	-0.00915
4	202.7780	2.67	0.0087	0.02232
5	260.3387	2.23	0.0091	-0.00355
6	316.2614	2.0	0.0078	-0.03588
7	334.1522	0.65	0.75	0.00521
8	347.1668	3.9	0.088	0.00469
9	388.1286	0.3	0.23	-0.01105
10	394.1834	0.3	0.1	-0.00029
11	414.9853	1.9	0.18	-0.00924
12	451.2226	8.57	0.078	-0.00182
13	466.3475	8.5	0.14	0.00130
14	504.7402	7.8	0.41	0.01524
15	507.2363	39.7	1.32	0.03394
16	537.3632	58.4	2.0	0.01038
17	575.3048	114.65	0.7	0.00005

Frequency for Full Truss and Percent Error in Frequency for Two Modal Synthesis Models Using 28 Degrees of Freedom Table V.

Full Truss (Hz)		Free Interface (X)	Fixed Interface (X)	Mode No.	Full Truss (Hz)	Free Interface (%)	Fixed Interface (%)
6.8 1777 8.9	88	6	0.00035	18	600.7099	0.19	0.18
136.3306 1.2	1.2		0.00037	61	628.5009	1.0	0.19
175.5505 5.1	5.1		0.0017	20	659.4299	0.2	0.075
202.7780 1.08	1.0	8	0.0038	21	668.5250	1.64	0.457
260.3387 0.99	0.9	6	0.0067	22	678.8447	9.0	0.143
316.2614 0.85	0.8	5	0.0029	23	681.8918	20.1	900.0
334.1522 0.4	4.0		61.0	24	690.5944	27.5	0.291
347.1668 1.58	1.58		0.03	25	750.0817	70.5	1.062
388.1286 0.08	0.0	~	0.12				
394.1834 0.03	0.03		0.04				
414.9853 0.9	6.0		90.0				
451.2226 3.0	3.0	_	0.03				
466.3475 2.6	2.6		0.0245				
504.7402 0.16	0.1	9	0.197				
507.2363 0.4	0.4	-	0.14				
537.3632 0.59	0	69	0.59				
575.3048 0.71	0.7	1	0.254				

Frequency for Full Truss and Percent Error in Frequency for Two Modal Synthesis Models Using 36 Degrees of Freedom Table VI.

Mode No.	· Full Truss (Hz)	Free Interface (%)	Fixed Interface (%)	Mode No.	Full Truss (Hz)	Free Interface (%)	Fixed Interface (%)
	1777.99	6.71	0.00023	81	600.7099	0.011	0.0565
2	136.3306	0.809	0.00015	19	628.5009	0.183	0.0151
3	175.5505	1,185	0.00034	20	659,4299	0.029	0.0154
4	202.7780	0.84	0.00252	21	668.5250	1.574	0.1027
5	260.3387	0.713	0.00161	22	678.8447	0.495	0.021
9	316.2614	0.689	0.0019	23	681.8918	1.650	0.00062
7	334.1522	0.092	9/90.0	24	690.5944	1.085	0.0622
80	347.1668	1.096	0.0159	25	750.0817	0.220	0.0673
6	388.1286	0.072	0.0301	26	757.5138	0.202	0.186
10	394.1834	0.012	0.00822	17	788.2198	0.642	0.552
-1	414.9853	0.651	0.0244	28	792.7149	4.107	0.0786
12	451.2226	1.969	0.00734	29	824.4077	3.734	0.149
13	466.3475	0.592	0.00442	30	840.6797	2.215	0.0964
14	504.7402	0.039	0.0139	31	854.6771	7.767	0.1146
15	507.2363	0.047	0.0255	32	883.3126	9.033	0.268
16	537.3632	0.443	0.160	33	909.3136	41.970	0.794
17	575.3048	0.147	0.0730				

Table VII. Transient Response and Percent Error in Displacement

Grid Pts.	Full Truss	B Substr.	F-B %	Full Truss	B. Substr.	F- BZ	Full Truss	B Substr.	F- B%
Times	28	41		29	42		30	43	
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0015	0.4786243	0.4785015	0.02566	0.499332	0.4993054	0.00533	0.4786243	0.4785015	0.02566
0.0030	2.070906	2.070847	0.00285	2.089915	2.089938	-0.00110	2.070906	2.070847	0.00285
0.0045	4.794056	4.793882	0.00363	4.813719	4.813558	0.00334	4.794056	4.793882	0.00363
0900.0	8.662573	8.662563	0.00012	8.682871	8.683060	-0.00218	8.662573	8.662563	0.00012
0.0075	13,65921	13.65901	0.00146	13.67806	13.67781	0.00183	13.65921	13,65901	0.00146
0600.0	19.79589	19.79587	01000.0	19.81609	19.81619	-0.00050	19.79589	19.79587	0.0000.0
0.0105	27.07146	27.07133	87000.0	27.09119	27.09122	-0.00011	27.07146	27.07133	0.00048
0.0120	35,47588	35.47573	0.00042	35,49501	35.49476	0.00070	35.47588	35.47573	0.00042

Table VIII. The Axial Force in Elements of B Substructure

	E	lement No.	
Times	111	112	113
0.0	0.0	0.0	0.0
0.003	235.1038	282.6908	235.1038
0.006	252.9327	304.9388	252.9327
0.009	179.1082	254.5373	179.1082
0.012	137.4126	223.7419	137.4126

Element No.

Times	141	142	143
0.0	0.0	0.0	0.0
0.003	185.0618	951.0315	185.0618
0.006	199.0282	1021.000	199.0282
0.009	177.9509	1021.209	177.9509
0.012	159.4311	959.688	159.4311

Table IX. Percent Frequency Error Using 62 Degrees of Freedom

	564	295	113	666	80,	576	778	0.5	91	68	741	941	92	181	.52	50	36
(%)	0.000264	0.001295	0.006511	0.023999	0.002708	0.015576	0.061877	0.015502	0.083516	0.080989	0.408741	0.156846	0.600192	0.462081	0.951452	0.106550	3.793036
Case 3	15.13293	61,69673	81,71170	135.0395	140.3182	201.6405	280.7314	281.8770	374.8512	421.0158	482.8321	561.4299	604.0111	703.3938	740.1181	840.3091	912.3958
(%)	0.000132	0.001583	0.007062	0.023999	0.014182	0.064537	0.031116	0.088864	0.023869	0.108231	0.292389	0.211292	0.816012	0.220907	1.622999	0.678068	5.725081
Case 2	15.13291	41.69685	81.71215	135.0395	140.3343	201.7213	280.6451	281.6908	374.6278	421.1304	482.2726	561.7351	605.3069	701.7052	745.0415	845.1065	929.3795
(%)	0.0000665	0.000432	0.001701	0.004518	0.000713	0.008879	0.002994	0.016273	0.011427	0.002163	0.020276	0.009098	0.035126	0.014068	0.075169	0.021027	0.172618
Case l (Hz)	15.13290	41.69637	81.70777	135.0132	140.3154	201.6091	280.5662	281.4865	374.5812	420.6842	480.9641	560.6017	600.6184	700.2570	733.6937	839.5912	880,5704
Full Beam (Hz)	15,13289	41.69619	81.70638	135.0071	140.3144	201.5912	280.5578	281.4407	374.5384	420.6751	480.8666	560.5507	600.4075	700.1585	733.1426	839.4147	879.0530
Mode No.	1	2	3	7	2	9	7	8	6	10	11	12	13	14	15	16	17

Table IX. Percent Frequency Error Using 62 Degrees of Freedom (concluded)

0.387913 1119.255 0.037076 0.986019 0.047434 0.060582 0.345291 0.083903 1.459748 0.120519 1 0.165140 2.461680 0.490217 1.983373	1	Case 1 (Hz) 978.7669	(%)	Case 2 1000.558	(%)	Case 3	(%)
	1042.146	746	0.387913			1119,255	7.815674
	1117.016	91	0.037076				
	1222.255	55	0.986019	-			
	1254.961	51	0.047434				
	1392.356	99	0,060582				
	1400.455	55	0.345291				
	1529.241	11	0.083903				
	1617.311	1	1.459748				
	1665.641	1	0.120519				
	1801.4451	51	0,165140				
	1849.961	1	2,461680				
	1941.881	31	0.490217				
	2070.290	90	1.983373				
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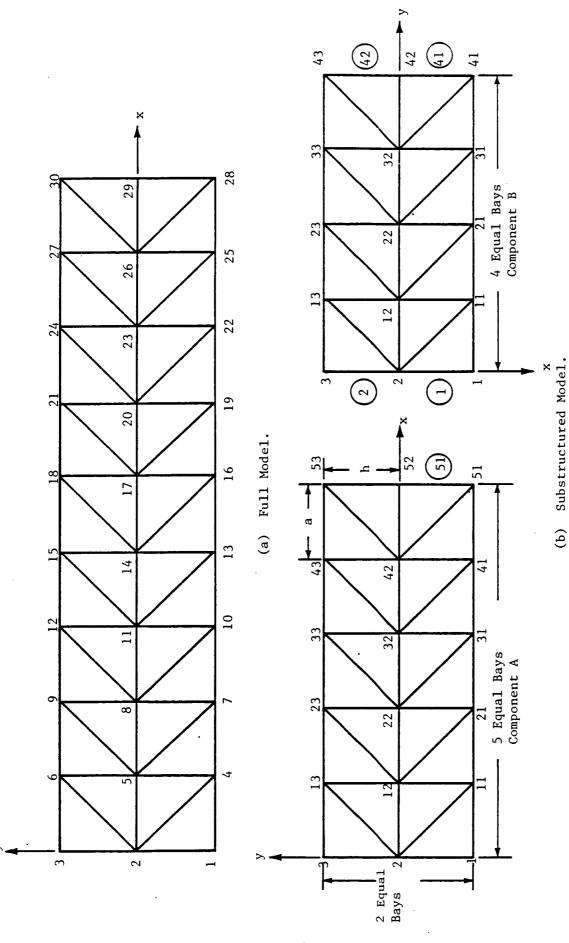


Figure 1. Truss Model.

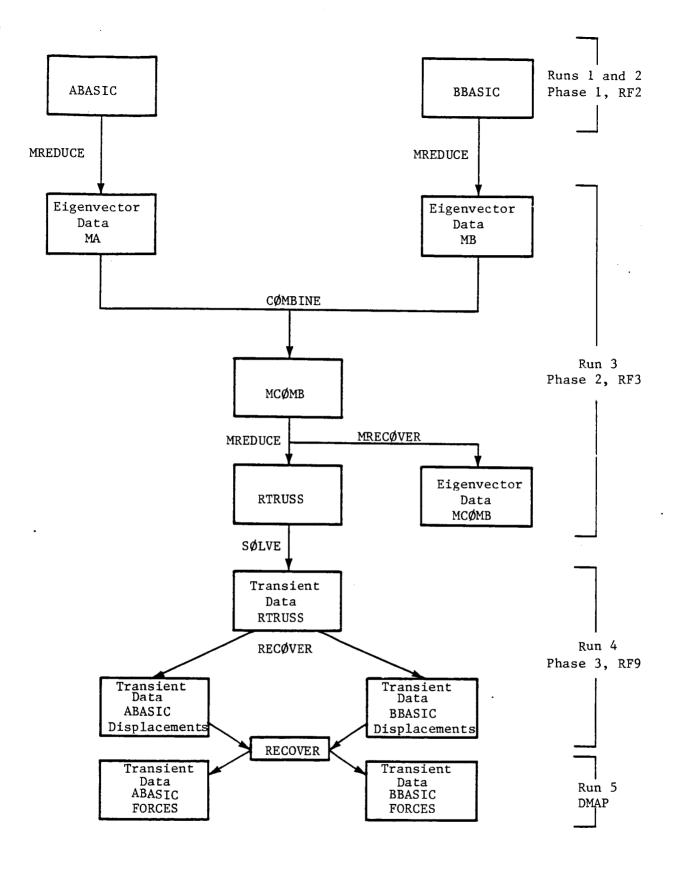
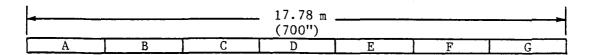
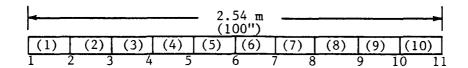


Figure 2. Substructure Formulation Tree and Solution Sequence



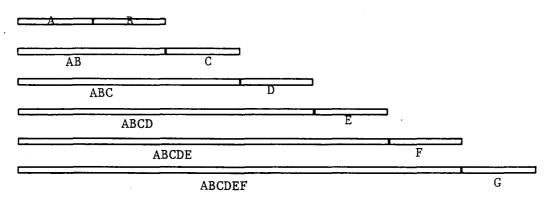
(a) Total beam model.



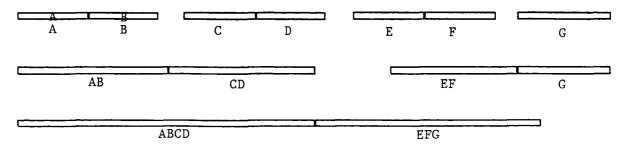
(b) Representative finite element model of any component.



(c) Case 1 - All components combined simultaneously.

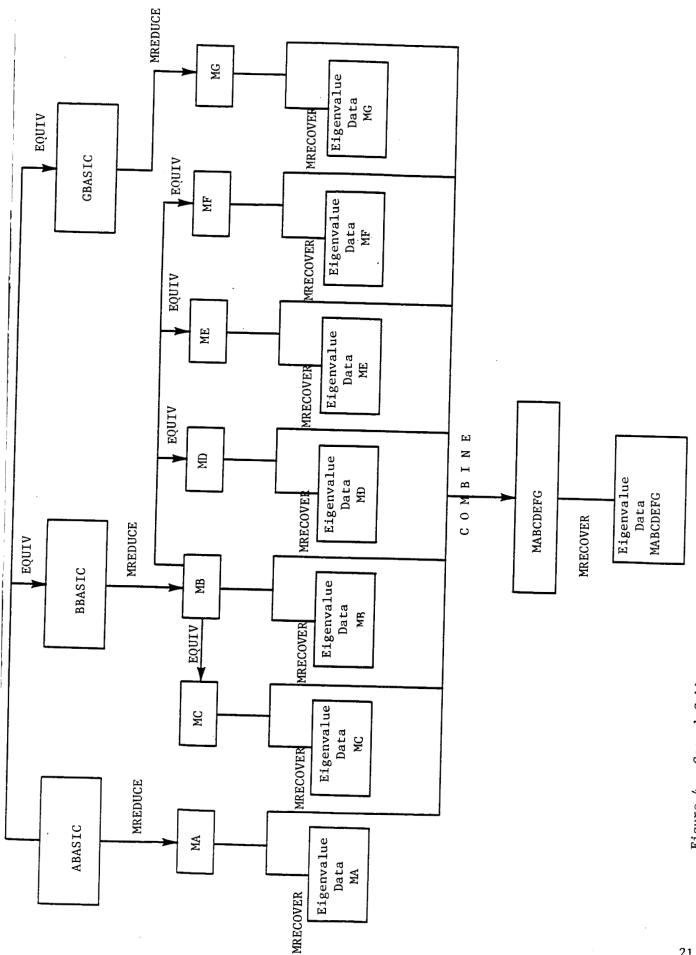


(d) Case 2 - Components combined sequentially.

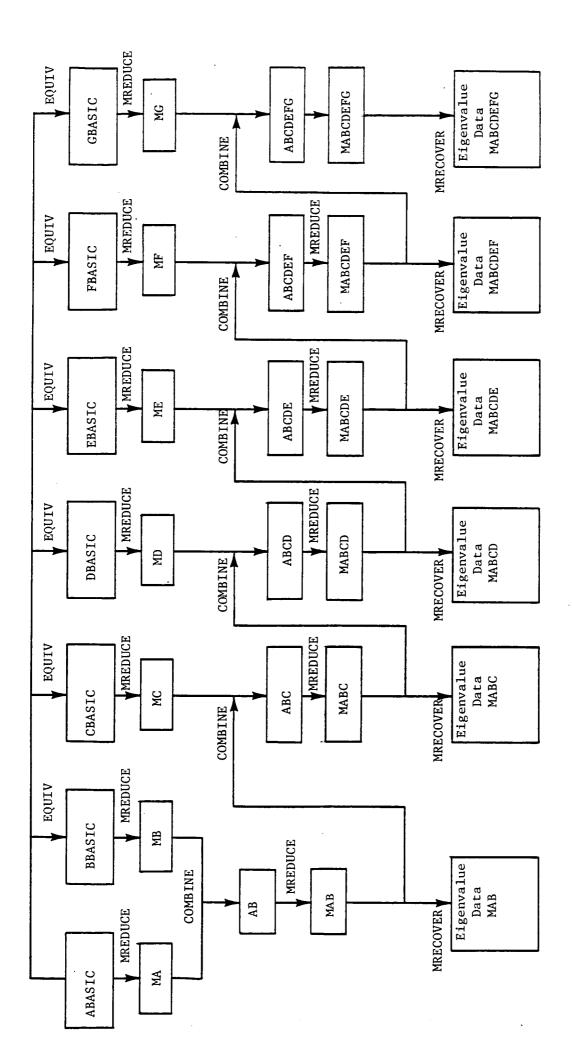


(e) Case 3 - Components combined in pairs. Pairs then combined sequentially.

Figure 3. Total Beam Model and Various Subdivided Representations.



Case 1 Subbeam Formulation Tree and Solution Sequence Figure 4.



Case 2 Subbeam Formulation Tree and Solution Sequence. Figure 5.

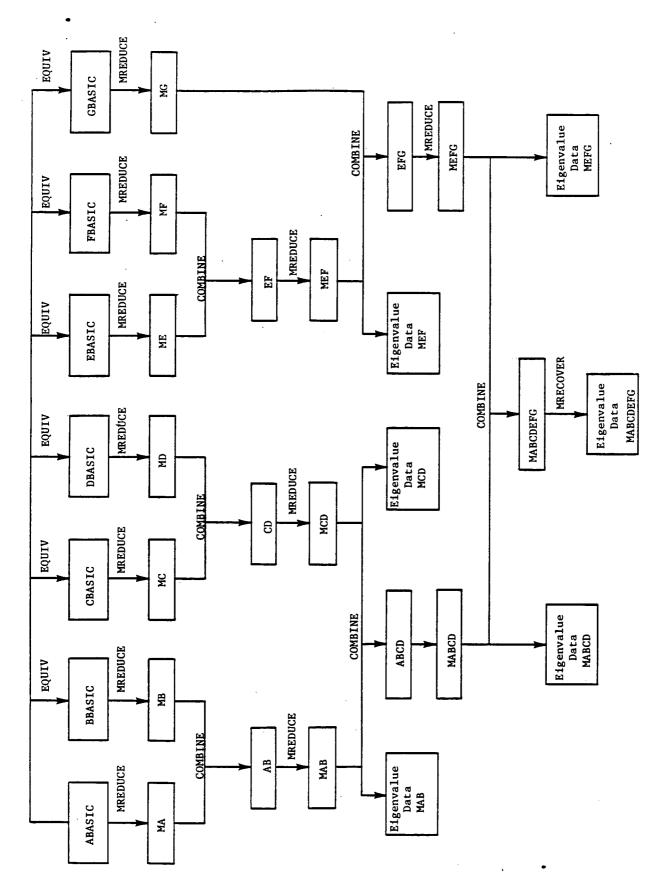


Figure 6. Case 3 Subbeam Formulation Tree and Solution Sequence

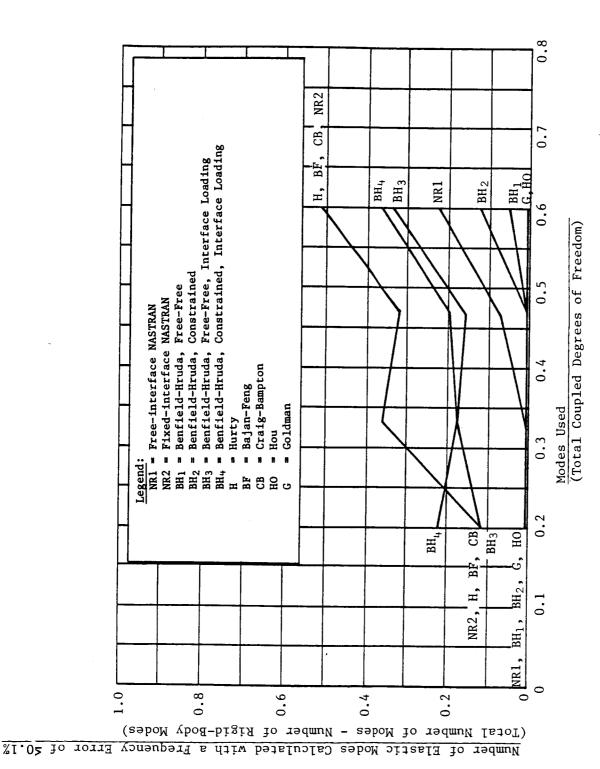
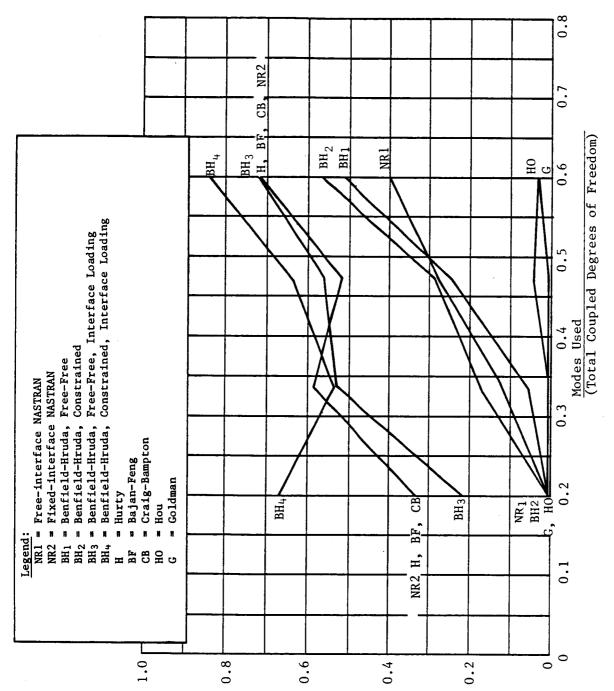
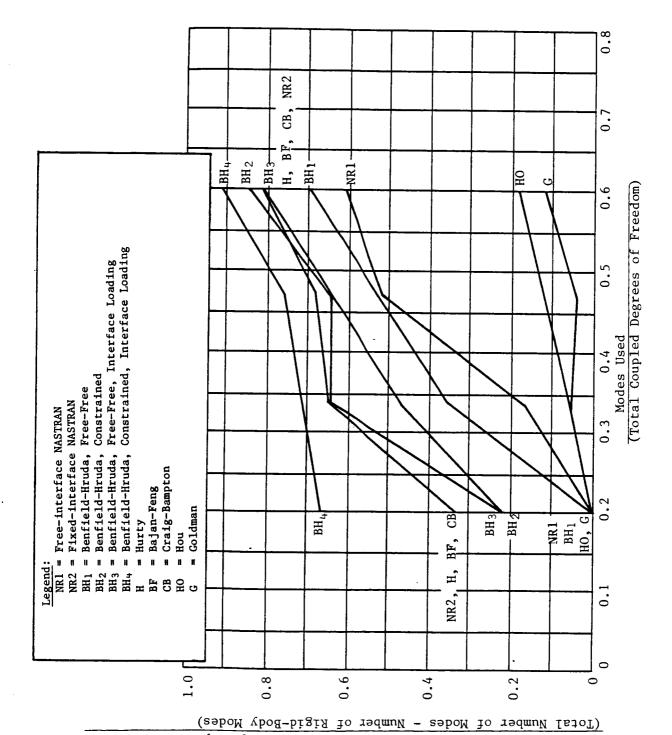


Figure 7. Comparison of Methods with Frequency Error of 0.1%.



Number of Elastic Modes Calculated with a Frequency Error of $\leq 0.5\%$ (Total Number of Modes - Number of Rigid-Body Modes)

Figure 8. Comparison of Methods with Frequency Error of 0.5%.



Number of Elastic Modes Calculated with a Frequency Error of <1.0%

Figure 9. Comparison of Methods with Frequency Error of 1.0%.

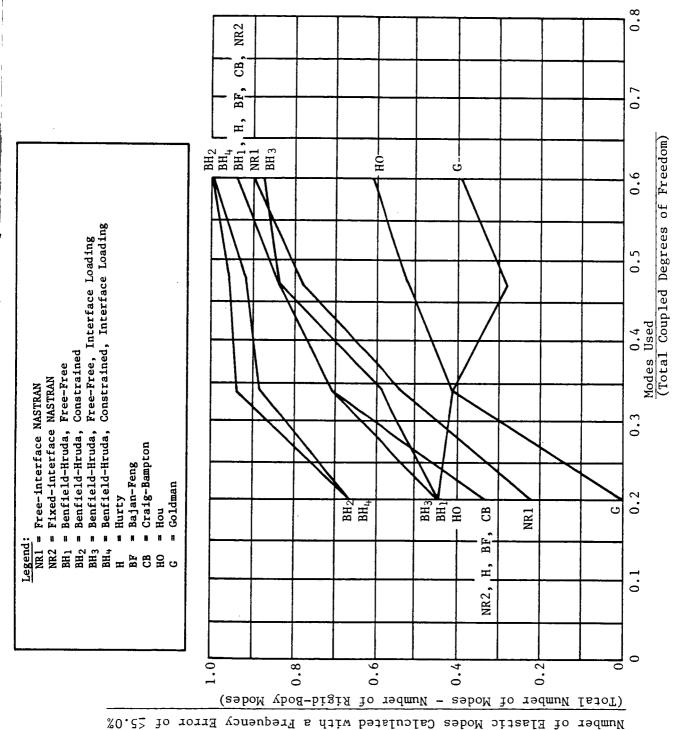
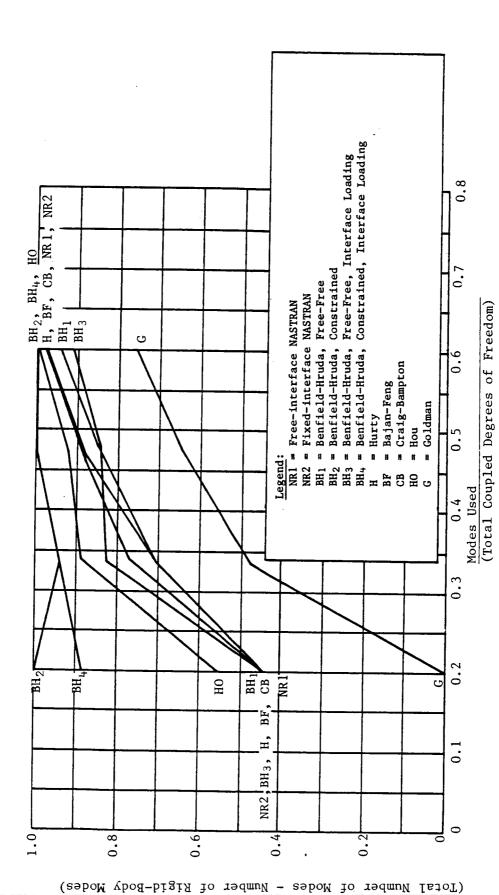


Figure 10. Comparison of Methods with Frequency Error of 5.0%.



Number of Elastic Modes Calculated with a Frequency Error of $\le 10.0\%$

Figure 11. Comparison of Methods with Frequency Error of 10.0%.

APPENDICES

APPENDIX A. Driver decks and sample bulk data for two components truss problem.

```
NASTRAN FILES = UMF $ CDC AND IBM
ID DEM2031, NASTRAN
APP DISP.SUBS
SOL 2,0
TIME 3
CEND
SUBSTRUCTURE PHASE1
PASSWORD = MDLSYN
SOF(1) = FT19,500, NEW $ CDC AND IBM
NAME = ABASIC
SOFPRINT TOC
ENDSUBS
TITLE = TRUSS DYNAMIC ANALYSIS USING
TITLE = TRUSS DYNAMIC ANALYSIS USING AUTOMATED MODAL SYNTHESIS LABEL = SUBSTRUCTURE 1, RUN 1, PHASE 1, RF 2
SUBTITLE = NASTRAN DEMONSTRATION PROBLEM NO. 2-3-1
BEGIN BULK
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       PROD
       ENDOATA
     NASTRAN FILES = UMF $ CDC AND IBM
ID DEM 2033, NASTRAN
APP DISP, SUBS
NASTRAN FILES = UMFTRAN
ID DEMONS
SOL SPP. SSUMS
SO
    ENDSUBS
TITLE = TRUSS DYNAMIC ANALYSIS USING AUTOMATED MODAL SYNTHESIS
SUBTITLE = NASTRAN DEMONSTRATION PROBLEM NO. 2-3-4
LABEL = MODAL REDUCE, COMBINE, MODAL RECOVERY, RUN 4, PHASE 2, RF 3
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		T/ALWAYS							
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		LOT=-1 5				·		·	
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PARAM		Y*/PFILE	/ / / / 5						
<u>COND</u> PLOT		MPPLOT 5	. EL SETS	CASECCAR	SPOT. FO	EXIN, SIL,	- FCT - /	OLOTY1/	
						·N·PFILE		L L O Î V Î \	<u></u>
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011005				N. GENEL			·		
PURGE					<u>1477984</u>	AA,MNN,MF	r + MAA + B	NN + BFF + B	AA,
COND		NOSIMP/O		<u> </u>					
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PARAM	//*ADD*/NOKGGX/1/0 \$
PARAM	//*ADD*/NOMGG/1/U \$
PARAM	//*ADD*/NOBGG=-1/1/0 \$
PARAM	//#ADD#/NOK4GG/1/0 \$
EMG	EST.CSTM.MPT.DIT.GEOM2,/KELM,KDICT,MELM,MDICT,BELM,BUICT/ S,
LMO	NANOK GGX / SANANOM GG / SANANOB GG / SANANOK 4 GG / / CAYA COUPMASS / CAYA
	CPBAR/C.Y.CPROD/C.Y.CPQUAD1/C,Y.CPQUAD2/C.Y.CPTRIA1/C.Y.
	CPTRIAZ/C,Y,CPTUBE/C,Y,CPQDPLT/C,Y,CPTRPLT/C,Y,CPTRBSC \$
PURGE	KGGX, GPST/NOKGGX/MGG/NOMGG \$
COND	LBLKGGX NOKGGX \$
	GPECT, KDICT, KELM/KGGX, GPST \$
EMA	LBLKGGX \$
LABEL	LBLMGG:NOMGG \$
COND	GPECT, MDICT, MELM/MGG, /-1/C, Y, WTMASS=1.0 \$
EMA	LBLMGG \$
LABEL	LBLBGG•NOBGG \$
COND	GPECT, BDICT, BELM/BGG, \$
EMA	
LABEL	LBLBGG \$ LBLK4GG,NOK4GG \$
COND	GPECT KDICT KELM/K4GG / NOK4GG \$
EMA	
LABEL	LBLK4GG \$ MNN,MFF,MAA/NOMGG \$
PURGE	
PURGE	BNN.BFF.BAA/NOBGG \$
COND	LBL1, GRDPNT \$
COND	ERROR3, NOMGG \$ BGPDP, CSTM, EQEXIN, MGG/OGPWG/V, Y, GRDPNT=-1/C, Y, WTMASS \$
<u>GPWG</u>	OGPWG,,,,,//S,N,CARDNO \$
OFP	
LABEL	LBL1 \$
EQUIV	KGGX + KGG/NOGENL \$
COND	LBL11.NOGENL \$ GEI.KGGX/KGG/LUSET/NOGENL/NOSIMP \$
SMA3	
LABEL	
PARAM_	//*MPY*/NSKIP/U/U \$ CASECC, GEOM4, EGEXIN, GPDT, BGPDT, CSTM, GPST/RG, JUSET, ASET/ LUSET/
GP4	SINIMPCF1/SINIMPCF2/SINISINGLE/SINIMIT/SINIREACT/SININSKIP/SINIMPCF1/SINIMPCF2/SININGLE/SINIMIT/SINIREACT/SININSKIP/SINIMPCF1/
	N, REPEAT/S, N, NOSET/S, N, NOL/S, N, NOA/C, Y, ASETOUT/ S, Y, AUTOSPC \$
	NAME PEATING TOO CODY CONTINUES OF TARRETT STATES OF THE S
PURGE	GM+GMD/MPCF1/GO+GQD/OMIT/KFS+PST+QP/SINGLE \$
COND	LBL4.GENFL \$
COND	LBL4.NOSIMP \$
PARAM	//*EQ*/GPSPFLG/AUTOSPC/0 \$
COND	LBL4, GPSPFLG 5
GPSP	GPL GPST USET SIL /OGPST/S N NOGPST \$
OFP	OGPST,,,,,//S,N,CARDNO \$
LABEL	LBL4 \$ KGG.KNN/MPCF1/MGG.MNN/MPCF1/ BGG.BNN/MPCF1/K4GG.K4NN/MPCF1 \$
EQUIV	KGG.KNN/MPCF1/MGG.MNN/MPCF1/ BGG.BNN/MPCF1/RTGGTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTT
COND	LBL2,MPCF1 \$
MCE1	USET + RG/GM \$
MCE2	USET . GM . KGG . MGG . BGG . K4GG / KNN . MNN . BNN . K4NN . S
LABEL	LBLZ \$
FOUTV	LBL2 \$ KNN.KFF/SINGLF/MNN.MFF/SINGLF/BNN.BFF/SINGLE/K4NN.K4FF/SINGLE \$
COND	LBL3.SINGLE \$

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SCEL	USET.KNN.MNN.BNN.K4NN/KFF.KFSMFF.BFF.K4FF 5
_LABEL	LBL3 \$
FQUIV	KFF · KAA/OMIT \$
EQUIV	MFF • MAA/OMIT \$
FOULV	BFF.BAA/OMIT S
EQUIV	K4FF•K4AA/OMIT \$
COND	LBL5.OMIT S
SMP1	USET.KFF/GO.KAA.KOO.LOO \$
COND	LBLM.NOMGG \$
SMP2	USET, GO, MEF/MAA \$
LASEL	LBLM \$
COND	LBLB, NOBGG \$
SMP2	USET, GO, BFF/BAA \$
LABEL	LBLB \$
COND	I BL 5 . NOK 4GG S
SMP2	USET, GO, K4FF/K4AA \$
LABEL	I BI 5 \$
PARAM	//*ADD*/DRY/1 /0 \$
LABEL	LBSBEG \$
DPD	DYNAMICS.GPL.SIL.USET/GPLD.SILD.USETD.TFPOOL.DLTNLFT.TRL
	FQDYN/LUSET/S.N.LUSETD/NOTEL/S.N.NODLT/NOPSDL/ NOFRL/S.N.
	NONI FT/S.N.NOTRL/NOFED//S.N.NOUE \$
COND	FRRORLINOTRI S
	PNI D/NONI FTS
PURGE	GO + GOD/NOUE/GM + GMD/NOUE \$
EQUIV	//*NOP*/AL WAYS=-1 \$
PARAM_	SLT.BGPDT.CSTM.SIL.EST.MPT.GPTT.EDT.MGG.CASECC.DIT/PG/LUSET/
_SSG1	
SSG2	NSKIP \$ USFT.GMKES.GOPG/QR.PO.PS.PL \$
RCOVR3	•PG•PS• • /UDVT•QAS•PPT•PSI• • •TOL /9 /*ABASIC */
KCUVR3_	NOUE \$
	USETD UDVT GOD . GMD . PST . KES / UPV QP/1/*DYNAMICS* \$
_SDR1	
_LABEL	LBL17 \$ CASECC, CASEXX/ALWAYS \$
EQUIV	CASEXX, CSTM, MPT, DIT, EQDYN, SILD, , , BGPDP, TOL, , UPV, EST, XYCDB,
SDR2	
	PPT/OPP1+0QP1+0UPV1+0ES1+0EF1+PUGV/*TRANRESP* \$
SDR3	OPP1.OUPV1.OES1.OEF1./OPP2.OUPV2.OES2.OEF2. \$
_0FP	OPPZ,OQPZ,OUPVZ,OEFZ,OESZ,//S,N,CARQNO \$
COND	P2.JUMPPLOT \$
PLOT	PLTPAR, GPSETS, ELSETS, CASEXX, BGPDT, EQEXIN, SIP, PUGY, GPECT, OES1/
	PLOTX2/NSIL/LUSEP/JUMPPLOT/PLTFLG/S.N.PFILE \$
PRTMSG	PLOTX2// \$
LABEL	P2 \$
XYTRAN	XYCD8.OPP2.OQP2.OUPV2.OES2.OEF2/XYPLTT/*TRAN*/*PSET*/S.N.PFILE/
	SINI CARDNO S
XYPLOT	XYPLTT// \$
LABEL	L8L18 \$
SOFUT	//DRY/*TOC
	* */* */* * \$
LABEL	LBSEND \$

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CROD 22			23	
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CROD41_			42	
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CROD11		3	11	
<u>CROD 117</u>		3	12	
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CROD 13			31	
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CROD 14.			41	
			42	
CROD 14:			43	
CROD217			13	
CROD 21		2	11	
CROD 22			21	· · · · · · · · · · · · · · · · · · ·
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CROD 23		22	33	
CROD 24		32	41	
CROD 24	<u> </u>	32	43	

APPENDIX A. (concluded)

GRDSET						- 3456
GRID	1		30.0	.0	. 0	
GRID	2		0	0	. 0	
GRID	3		-30.0	.0	. 0	
GRID	11		30.0	40.0	. 0	
GRID	12		. 0	40.0	0	
GRID	13		-30.0	40.0	_0	
GRID	21		30.0	80.0	. 0	
GRID	22		. Ō	80.0	0	
GRID	23		-30.0	80.0	. 0	
GRID	31		30.0	120 0	0	
GRID	32		. 0	120.0	0	
GRID	33		-30.0	120.0	.0	
GRID	41		30.0	160.0	0	
GRID	42		0	160.0	0	
GRID	43		-30.0	160.0	. 0	
MATI	1	10.0+6		.3	2.5-4	
_PROD	1	1	3			
DAREA	980	42	1	1.0+3		
TLOAD 2	101	980			0.0	0.12
E 159602	1 8 1	3.00	3.0-3	ৰ	0-0-	0-12
ENDDATA	T •	- -				
/EOF						
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APPENDIX B. Driver decks and sample bulk data for beam problem of case 1.

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NASTRAN FILES = UMF $ CDC AND IBM
ID DEM2031, NASTRAN
APP DISP, SUBS
SOL 3,0
TIME 3
CEND
SUBSTRUCTURE PHASE1
PASSWORD = MDLSYN
SOF(1) = FT17,500, NEW $ CDC AND IBM
NAME = ABASIC
SOFPRINT TOC
ENDSUBS
TITLE = BEAM DYNAMIC ANALYSIS HELD
                  = BEAM DYNAMIC ANALYSIS USING AUTOMATED MODAL SYNTHESIS = SUBSTRUCTURE 1, RUN 1, PHASE 1, R6 2
  TITLE = BEAM
 LABEL = SU
BEGIN BULK
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 ENDDATA
NASTRAN FILES = UMF $ CDC AND IBM ID DEM2032, NASTRAN APP DISP, SUBS SOL 3, 0 TIME 5 CEND SUBSTRUCTURE PHASE2 PASSWORD = MDLSYN SOF(1) = FT17,500 $ CDC AND IBM EQUIV ABASIC, BBASIC PREFIX B EQUIV ABASIC, GBASIC PREFIX G MREDUCE ABASIC NAME MA
MAME MA
BOUNDARY 20
FIXED 20
METHOD 1
MREDUCE BBASIC
NAME MB
BOUNDARY 2
```

(concluded) APPENDIX B. FIXED 2 METHOD 2 MREDUCE GBASIC NAME MG BOUNDARY 3 BOUNDARY 3 FIXED 3 METHOD 3 EQUIV MB, MC PREFIX C EQUIV MB, MD PREFIX D EQUIV MB, ME PREFIX E EQUIV MB, MF PREFIX F COMBINE MA, MB, MC, MD, ME, MF, MG NAME ABCCE 0.01 OUTPUT 2,7,12 COMPONENT MB TRANSFORM 2 COMPONENT MC COMPONENT TRANSFORM COMPONENT MC MD TRANSFORM COMPONENT ME COMPONENT ME TRANSFORM 5 COMPONENT MF TRANSFORM 6 COMPONENT MG TRANSFORM 7 MREDUCE ABCDEFG NAME BEAM BOUNDARY 20 METHOD 22 METHOD 22 METHOD 21 SOFPRINT TOC SOFPRINT TOC ENDSUBS TITLE=BEAM DYNAMIC ANALYSIS USING AUTOMATED MODAL SYNTHESIS SUBTITLE=NASTRAN DEMONSTRATION PROBLEM NO. 2-3-2 LABEL=MODAL REDUCE, COMBINE, MODAL, RECOVERY, RUNZ, PHASE2 BEGIN BULK BDYC 2 BBASIC 50 BDYC 3 GBASIC 40 BBASIC GBASIC ABASIC 126 126 126 BDYC BDYS1 BDYS1 20 30 ЗŌ 11 4050 BDYSI 11 TRANS +T2 TRANS +T3 Ž 150. 100. Ò. 0. 0. 100. **+T2** l. 0. 0 ŽÕO. 0. 0. 0. 200. **+T3 250.** 0. 0. TRANS šŏο. 0. 0. 300. +T4 0. 350. 0. 400. +T4 0. TRANS 0. 0. 400. 0. +T5 1. 450. 0. 0. 500. TRANS 0. 0 . 500. U. ı. +T6 Š50. 600. 0. TRANS 0. 600. 0. 0. +T7 650. 0 EİĞR ĬŇV 3000.00 10 10 +E1 MAX 2 +E1 É Î ĜR .0 INV 3000.00 10 10 +E2 XAM E EIGR +E3 EIGR +E22 . 0 10 INV 3.000.00 10 **+E3** MAX 22 INV . 0 40 40 2000.0 +E22 MAX ENDDATA

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NASTRAN FILES = UMF $ CDC AND IBM
ID DEM2031, NASTRAN
APP DISP, SUBS
SOL 3, 0
TIME 3
CEND
SUBSTRUCTURE PHASE1
PASSWORD = MDLSYN
SOF(1) = FT17,500, NEW $ CDC AND IBM
NAME = ABASIC
SOFPRINT TOC
ENDSUBS
TITLE = BEAM DYNAMIC ANALYSIS USING
LABEL = SUBSTRUCTURE 1, RUN 1, PHASE
                     = BEAM DYNAMIC ANALYSIS USING AUTOMATED MODAL SYNTHESIS = SUBSTRUCTURE 1, RUN 1, PHASE 1, R6 2
 LABEIN
BAGGOR
CBARR
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METHOD 24
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MREDUCE ABCDEF
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COMPONENT MF
TOLERANCE 0,01
OUTPUT 2,7,12
COMPONENT MF
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COMPONENT MG
TOLERANCE 0,01
OUTPUT 1,5,6,9,10
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APPENDIX C. (concluded)

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NAME = ABASIC

SOFPRINT TOC

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TITLE = BEAM DYNAMIC ANALYSIS USING AUTOMATED MODAL SYNTHESIS

LABEL = SUBSTRUCTURE 1, RUN 1, PHASE 1, R6 2

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TOLERANCE 0.01
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MREDUCE ABCD
NAME MABCD
BOUNDARY 30
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METHOD 25
COMBINE MEF, MG
NAME EFG
TOLERANCE 0.01
OUTPUT 2,7,12
COMPONENT MG
TRANSFORM 3
 MREDUCE EFG
NAME MEFG
BOUNDARY 35
FIXED 35
METHOD 25
COMBINE MABCD + MEFG
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COMBINE MABCD.MEFG
NAME ABCDEFG
TOLERANCE 0.01
OUTPUT 2,7,12
COMPONET MEFG
TRANSFORM 5
MREDUCE ABCDEFG
NAME BEAM
BOUNDARY 20
METHOD 25
OUTPUT 1,5,6,9,10
SOFPRINT TOC
ENDSUBS
TITLE=BEAM DYNAMIC ANALYSIS USING AUTOMATED MODAL SYNTHESIS
SUBTITLE=NASTRAN DEMONSTRATION PROBLEM NO. 2-3-2
LABEL=MODAL REDUCE.COMBINE,MODAL,RECOVERY,RUN2,PHASE2
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APPENDIX D. (concluded)

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1. Report No.	2. Government Accession No.	3. Recipient's Catalog No.
4. Title and Subtitle		5. Report Oate June 1983
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Norfolk, Virginia 23508		NAG 1-301
2. Sponsoring Agency Name and Address		13. Type of Report and Period Covered Contractor Report
National Aeronautics and S	Space Administration	11/1/82 - 6/15/83
Hampton, Virginia	•	14. Sponsoring Agency Code
5. Supplementary Notes		
Langley Technical Monitor	: Joseph E. Walz	
i. Abstract		
NASTRAN® and several other based on a truss or beam ponent substructure is re	ner modal synthesis result having redundant or point educed to modal and bounda	RAN® modal synthesis, full structure s (truss only). The results are interface connections. Each com-ry degrees of freedom prior to the
NASTRAN® and several other based on a truss or beam ponent substructure is resubstructure combine open	ner modal synthesis result having redundant or point educed to modal and boundaration. The combination salso reduced to modal degr	s (truss only). The results are interface connections. Each com-
NASTRAN® and several oth based on a truss or beam ponent substructure is resubstructure combine oper the component modes, is a transient analysis rigid	ner modal synthesis result having redundant or point educed to modal and boundaration. The combination salso reduced to modal degration.	s (truss only). The results are interface connections. Each com-ry degrees of freedom prior to the tructure, formulated in terms of
NASTRAN® and several off based on a truss or beam ponent substructure is re substructure combine open the component modes, is a	ner modal synthesis result having redundant or point educed to modal and boundaration. The combination salso reduced to modal degration.	s (truss only). The results are interface connections. Each com- ry degrees of freedom prior to the tructure, formulated in terms of ees of freedom for solution by the